

Fig. 1

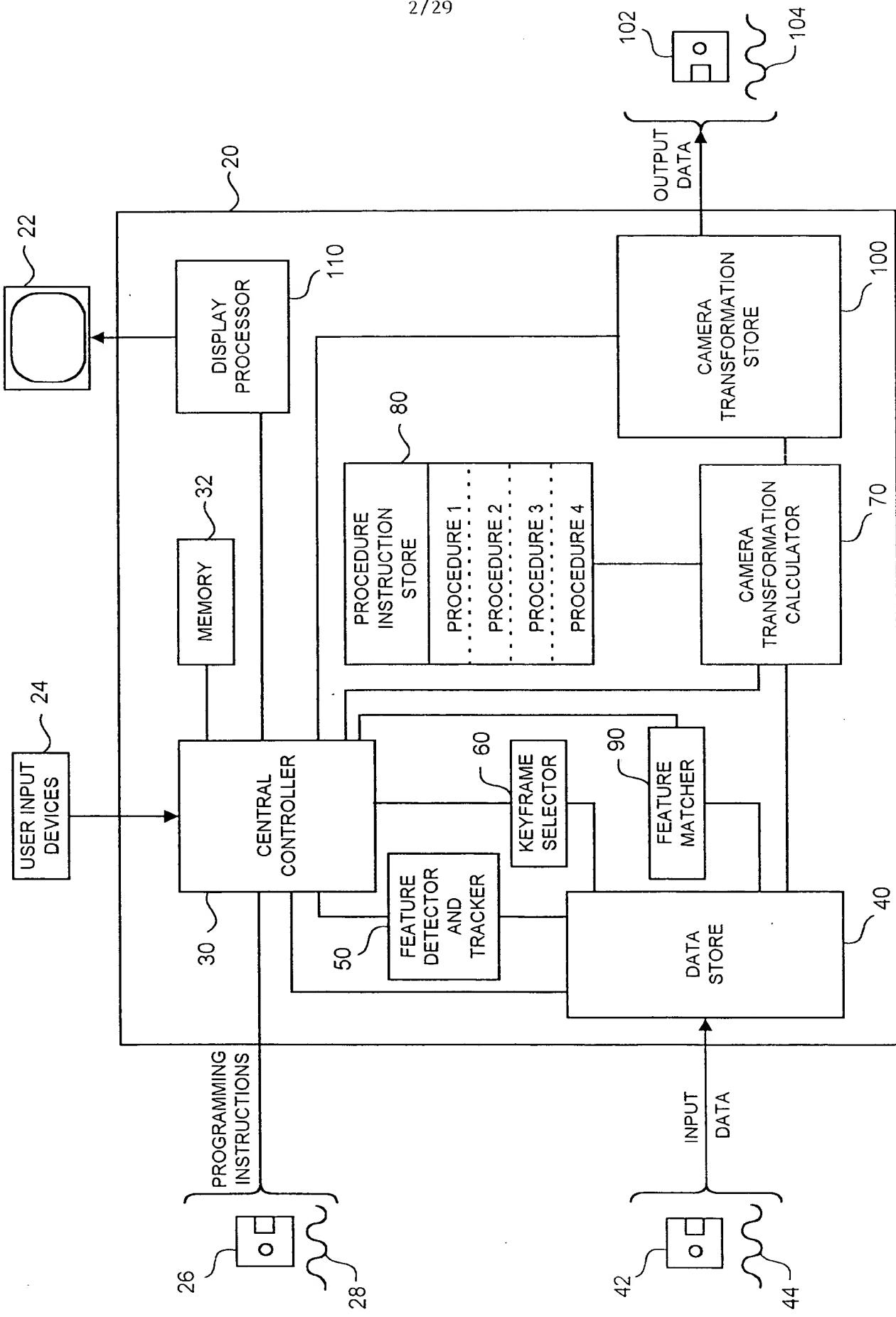


Fig. 2

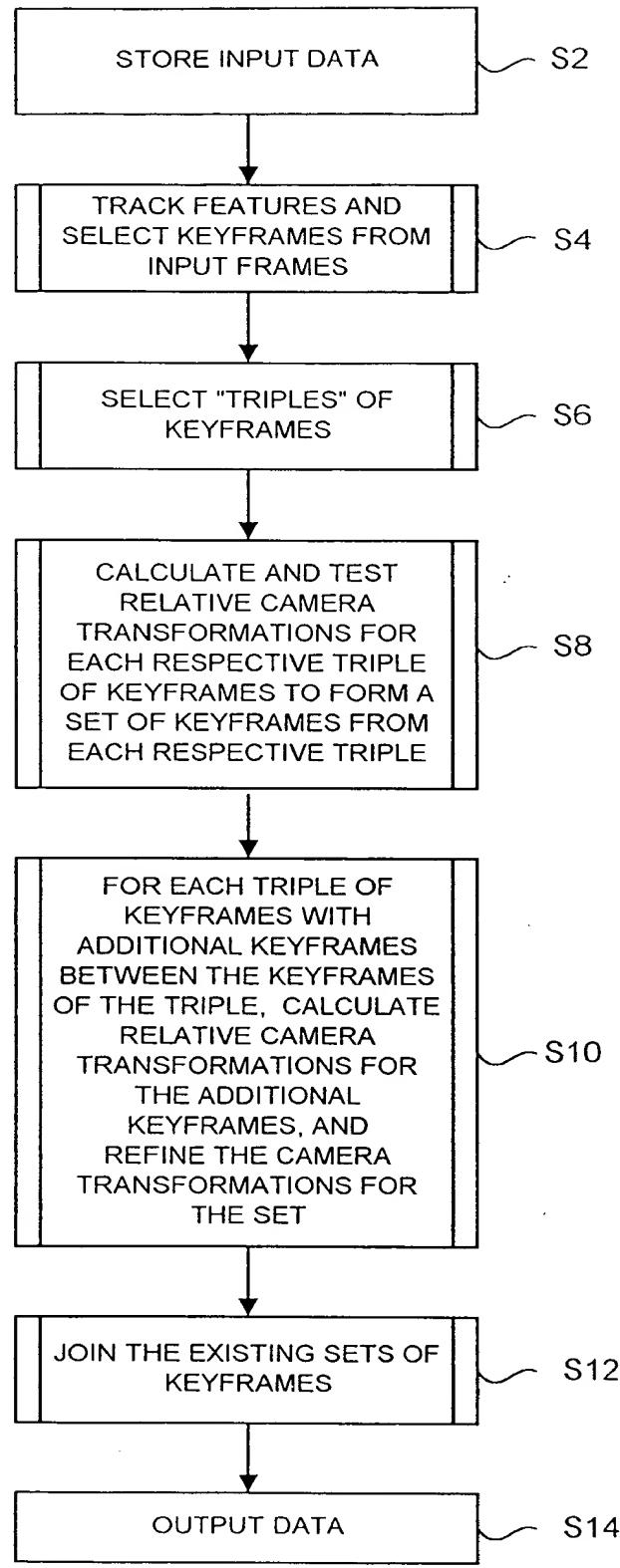
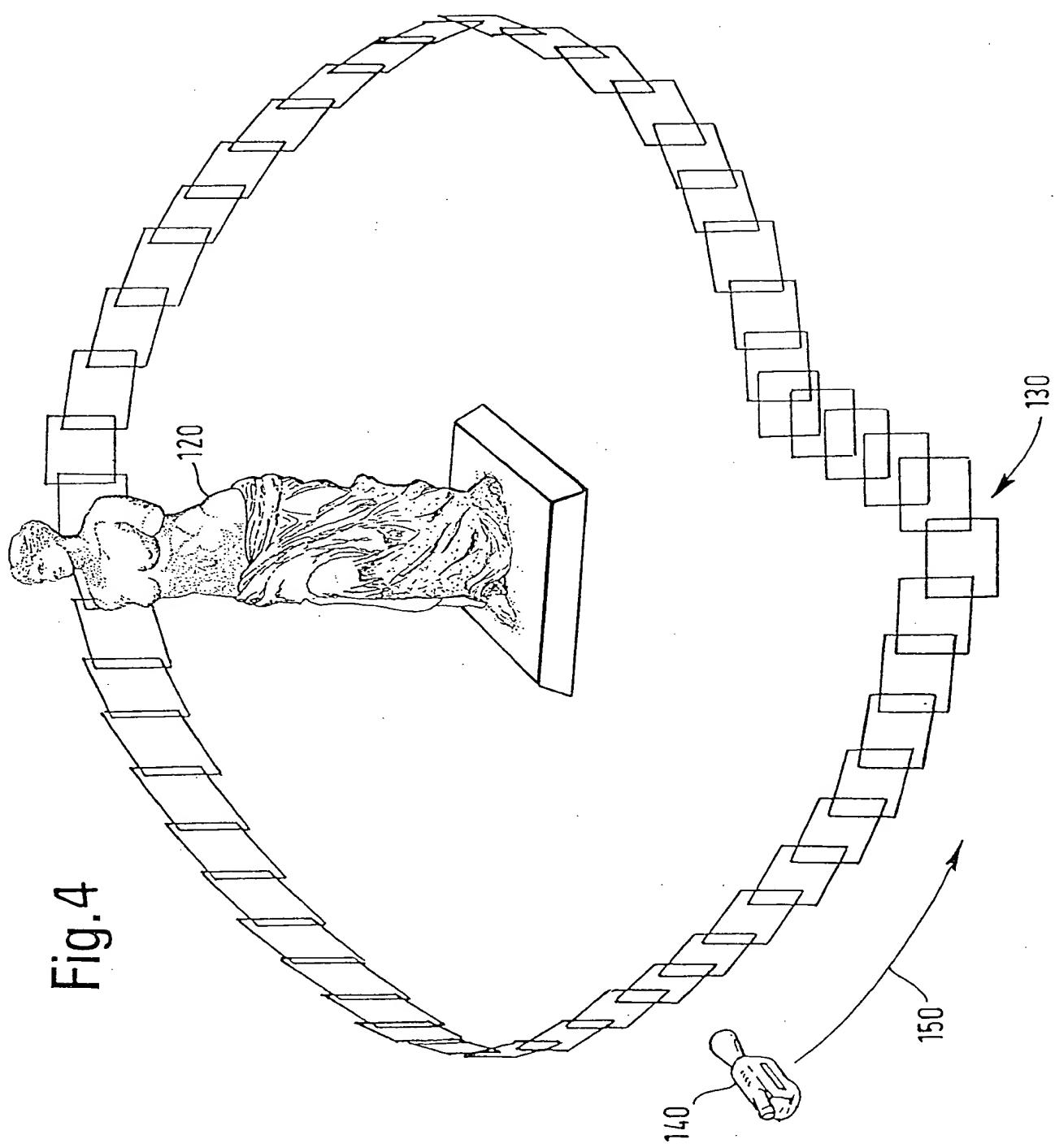


Fig. 3



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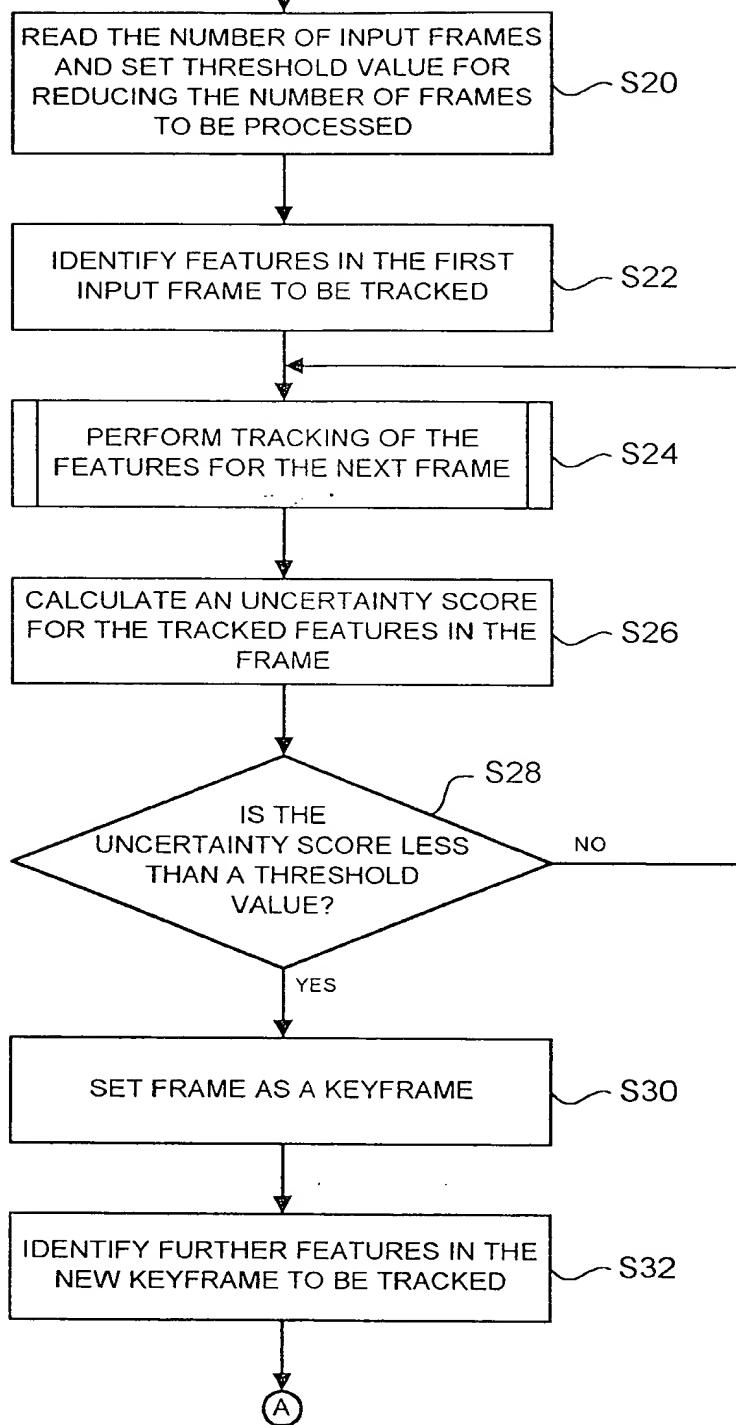


Fig. 5

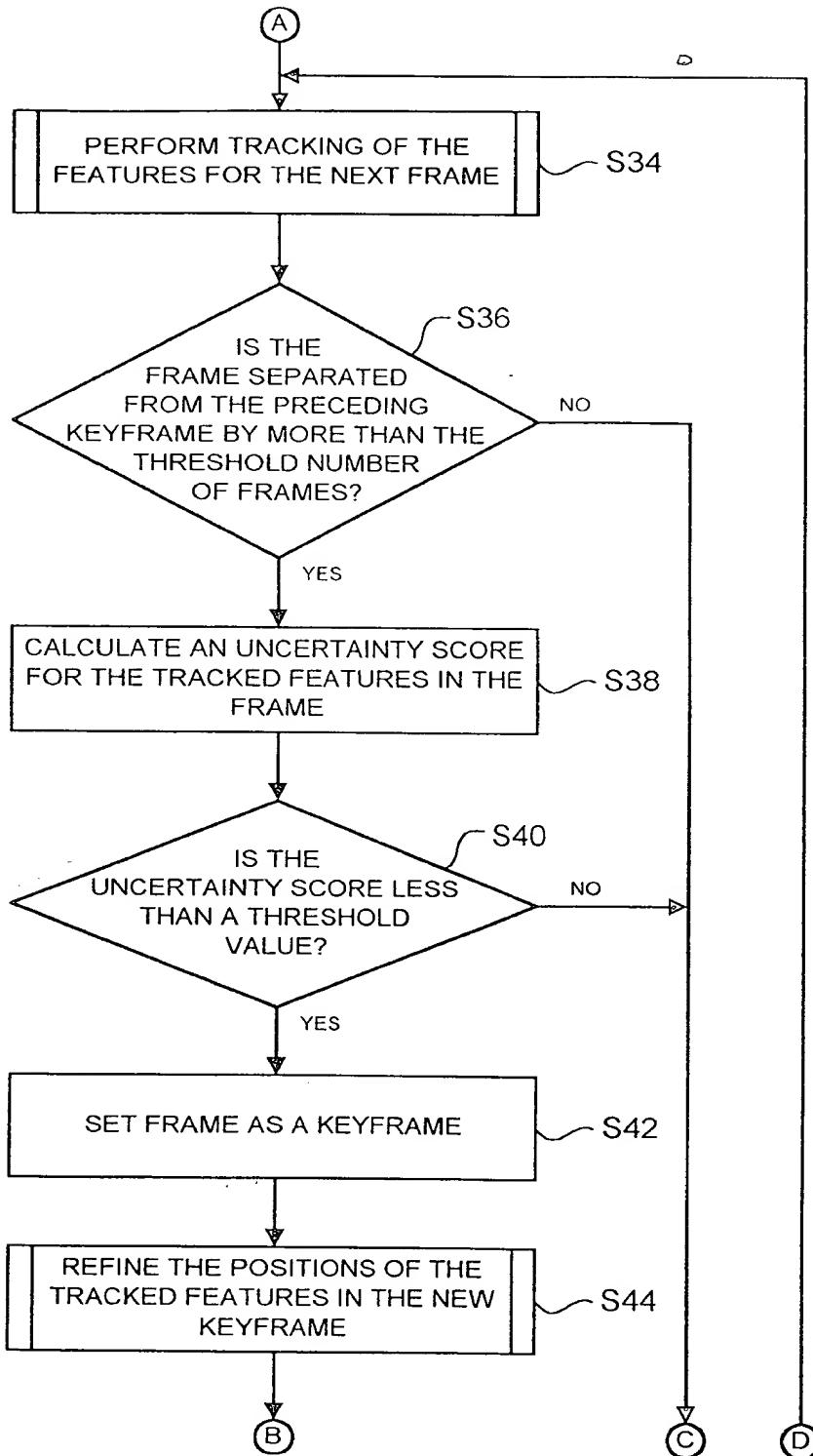


Fig. 5 (cont)

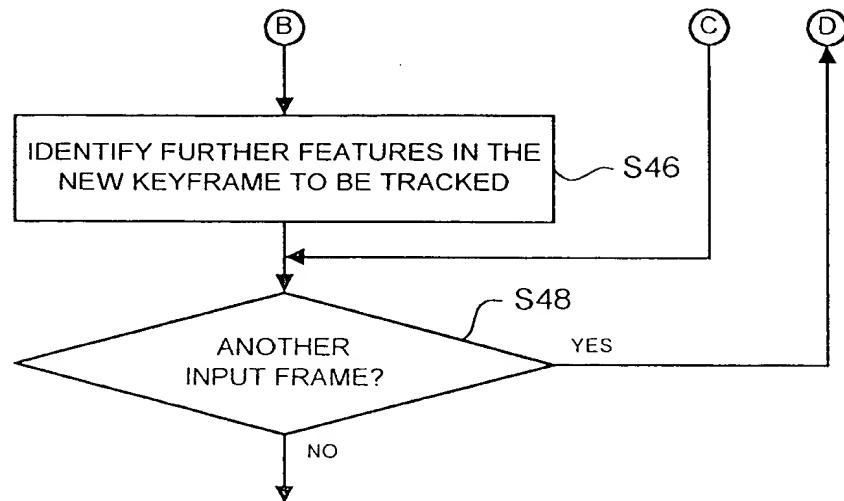


Fig. 5 (cont)

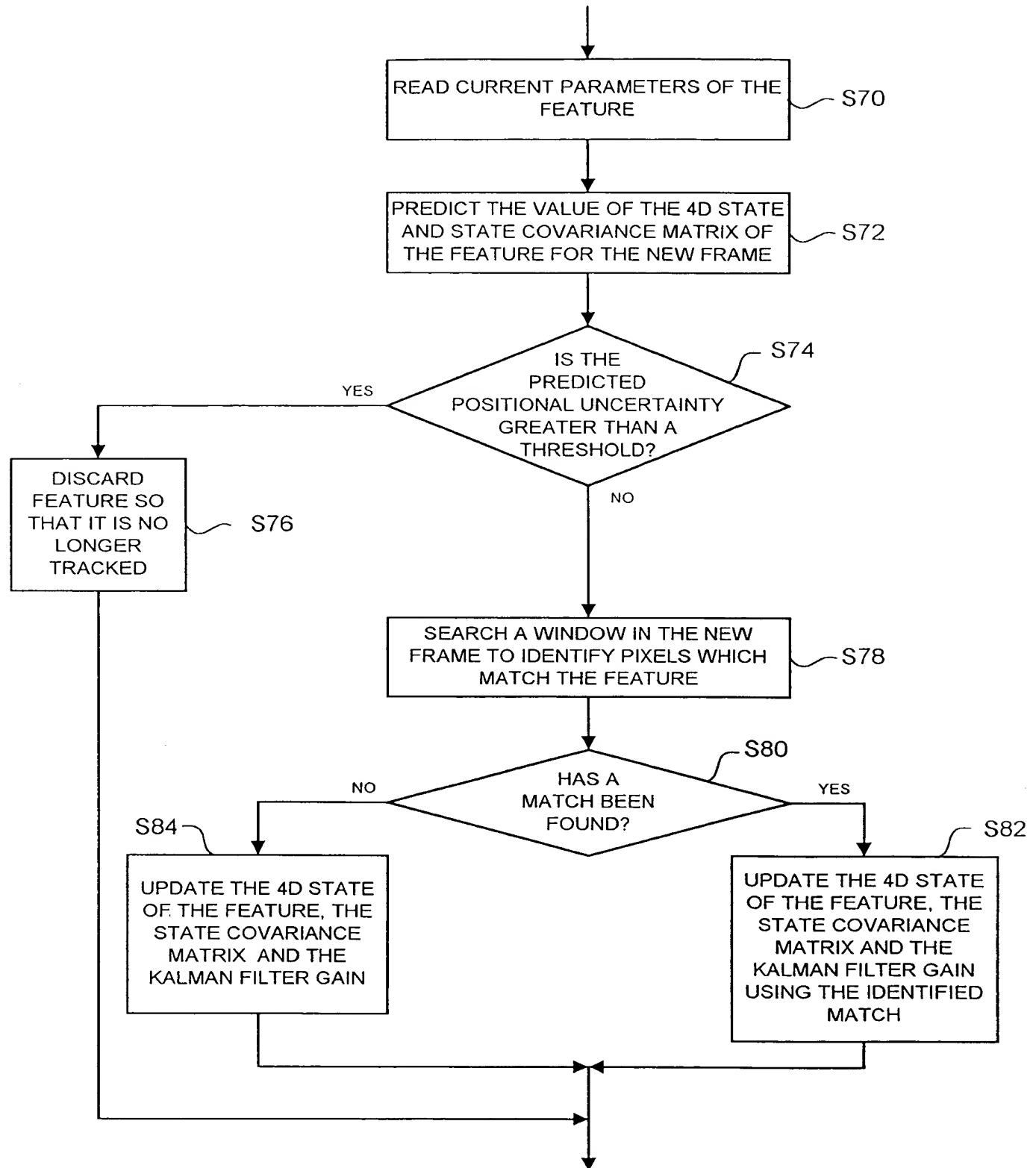


Fig. 6

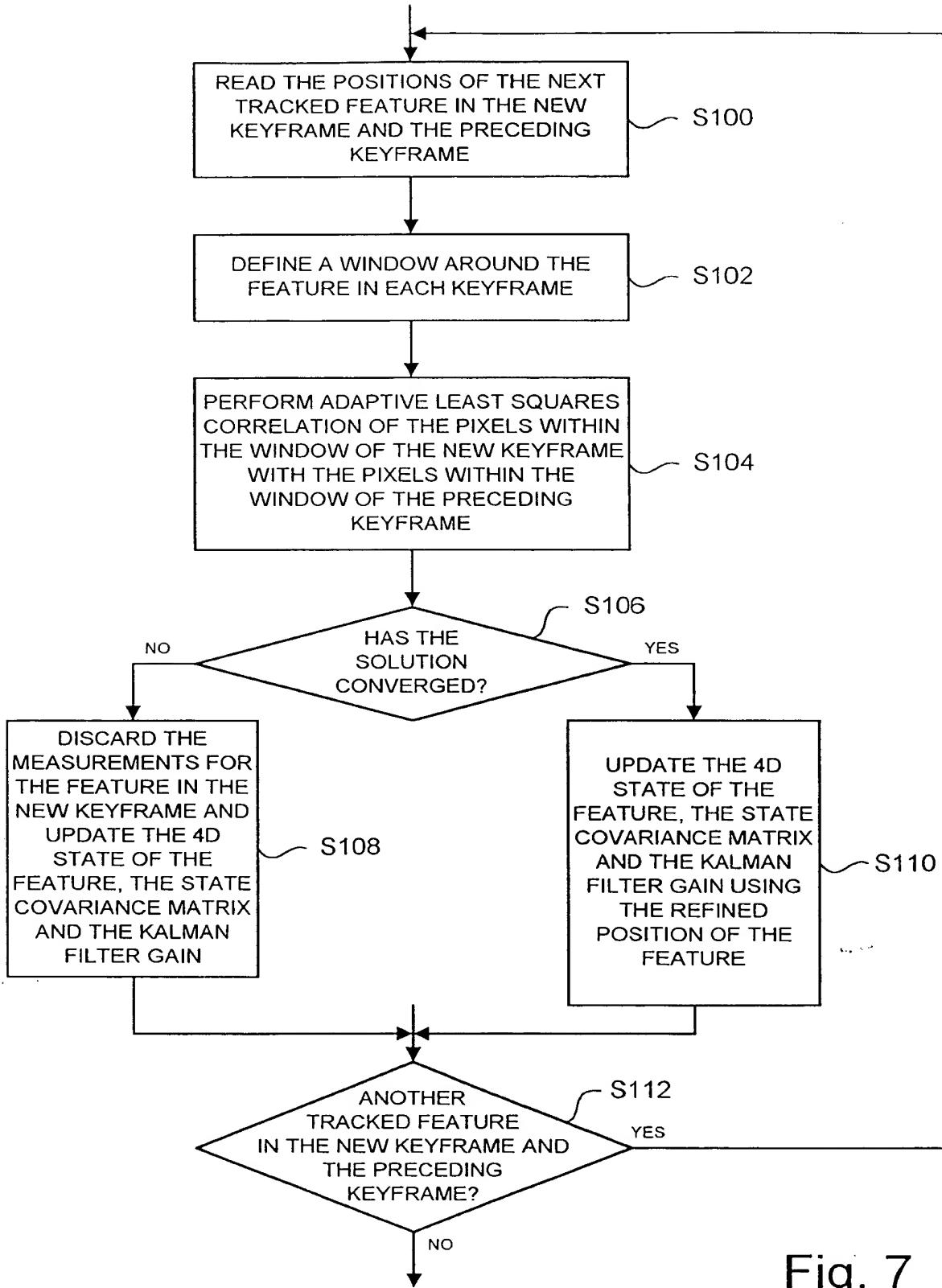


Fig. 7

Fig. 8a

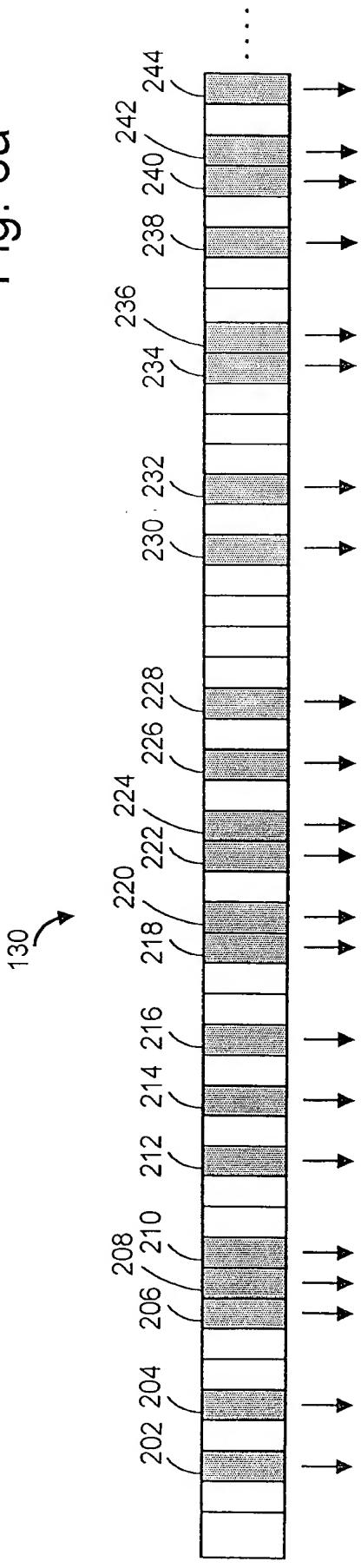
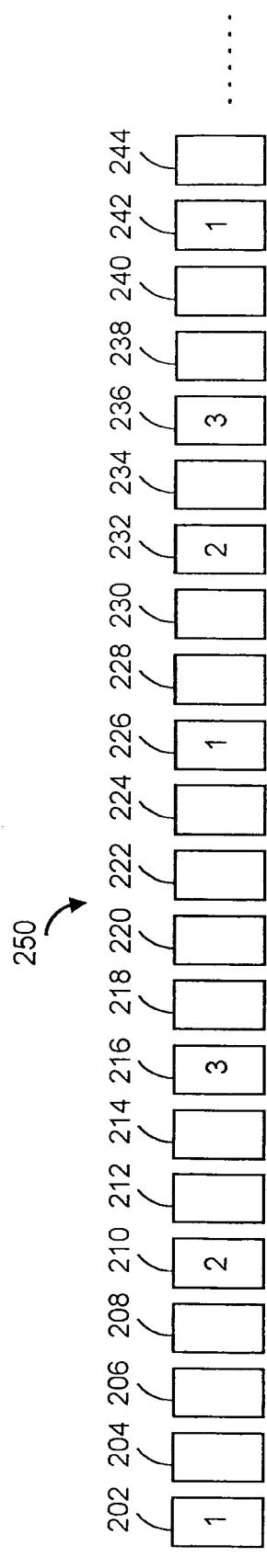


Fig. 8b



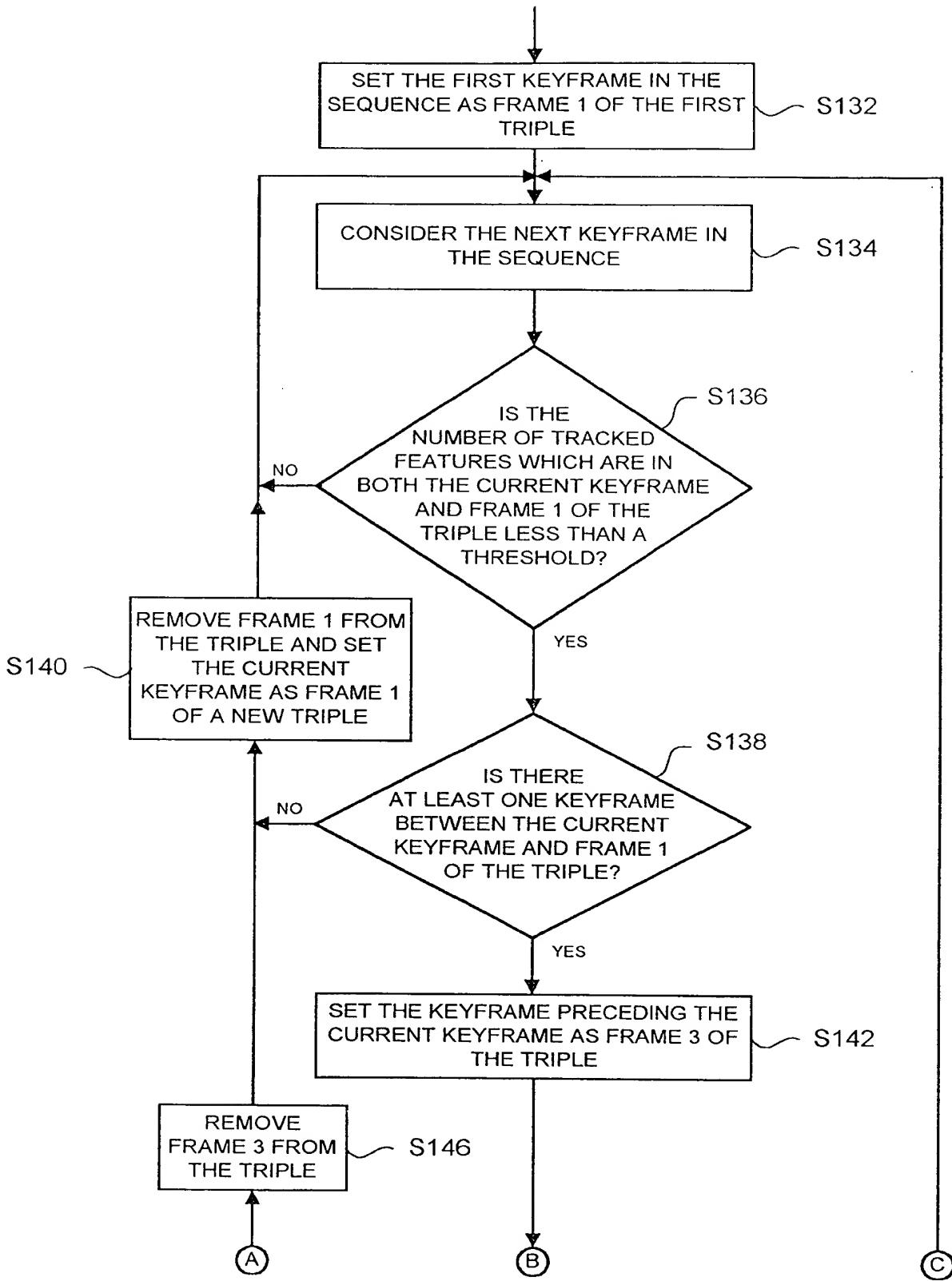


Fig. 9

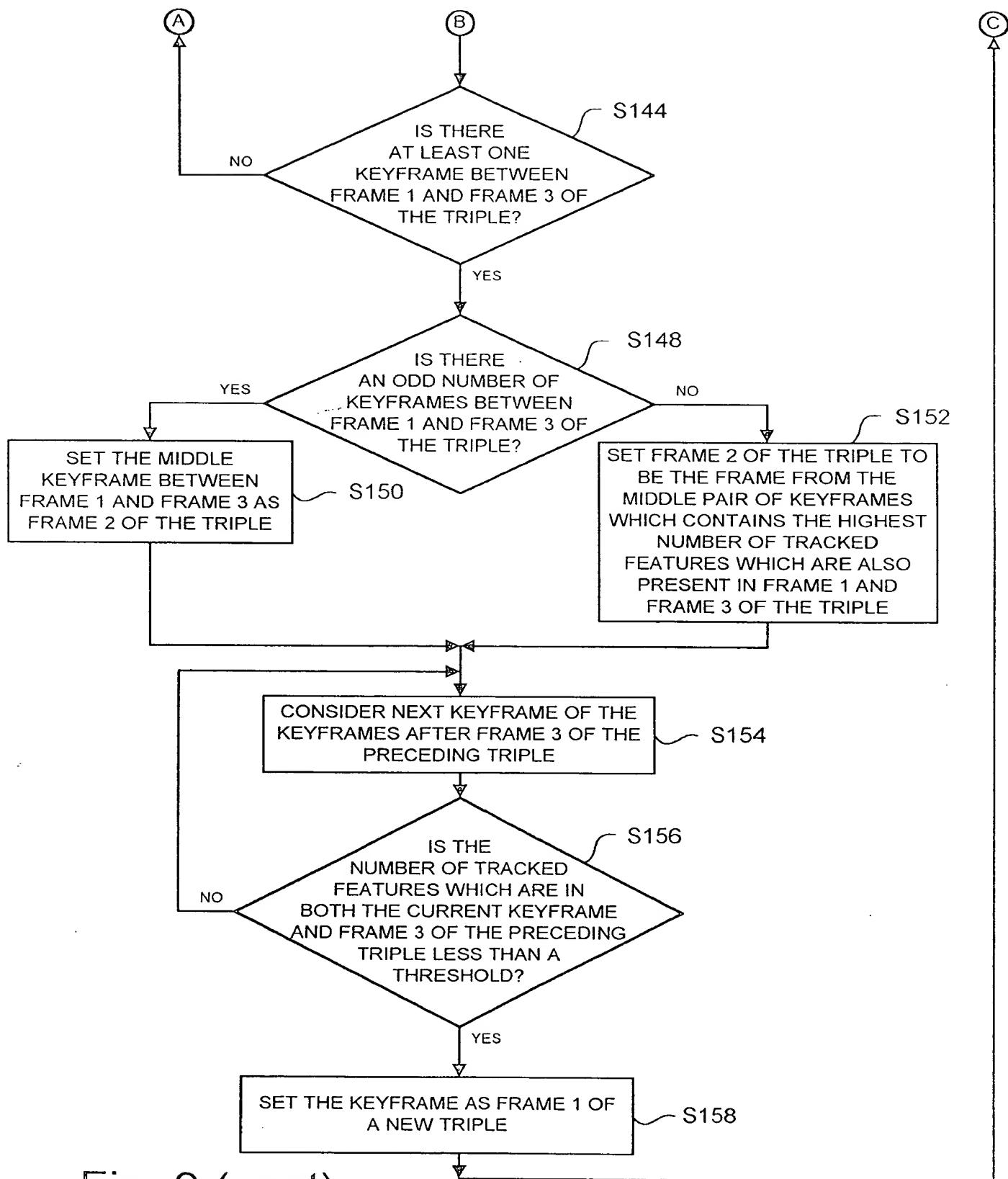


Fig. 9 (cont)

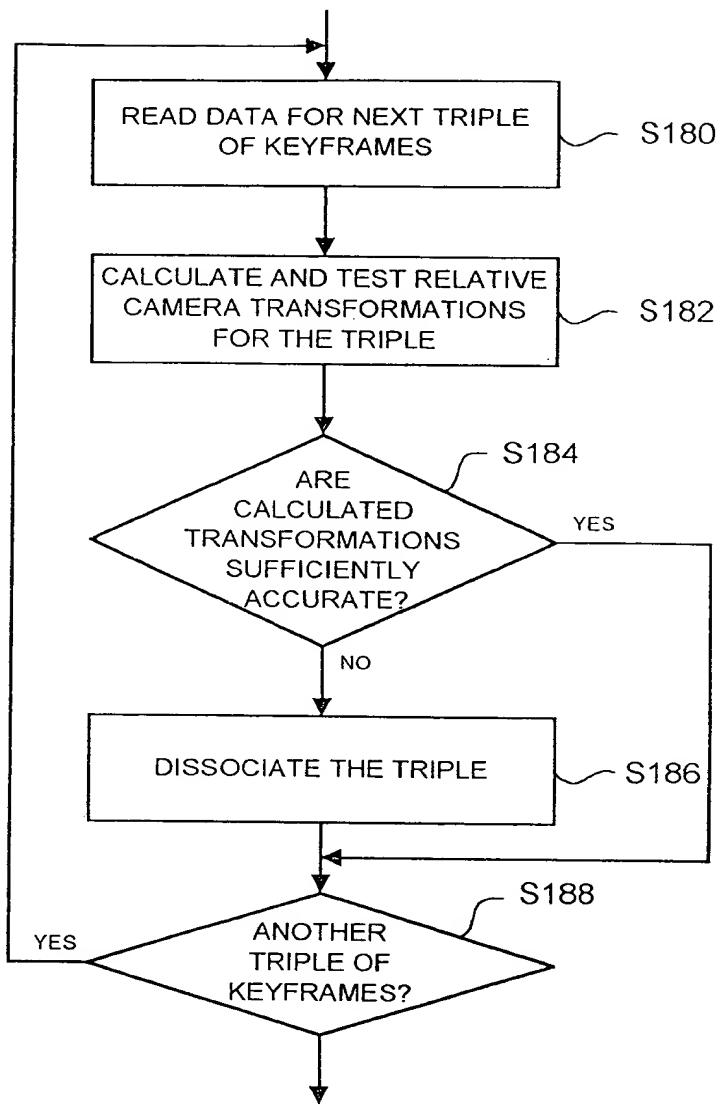
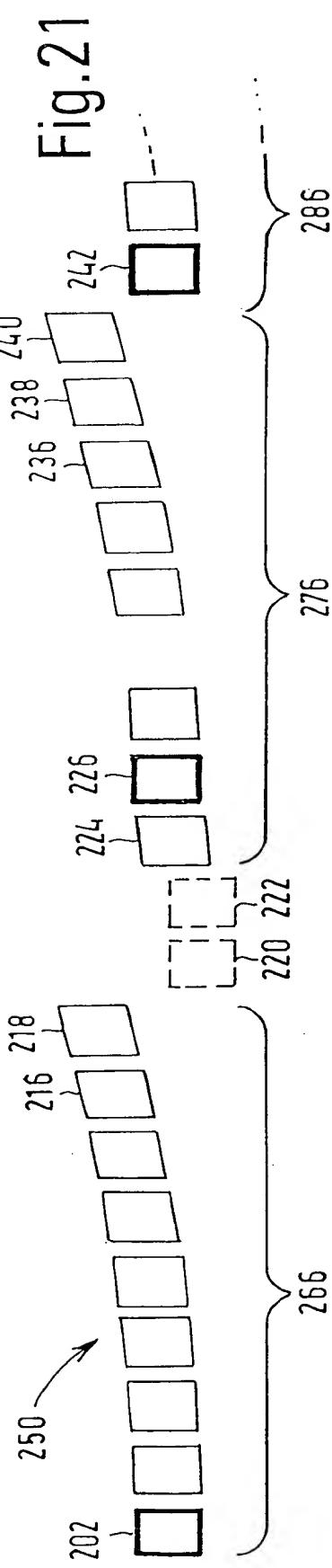
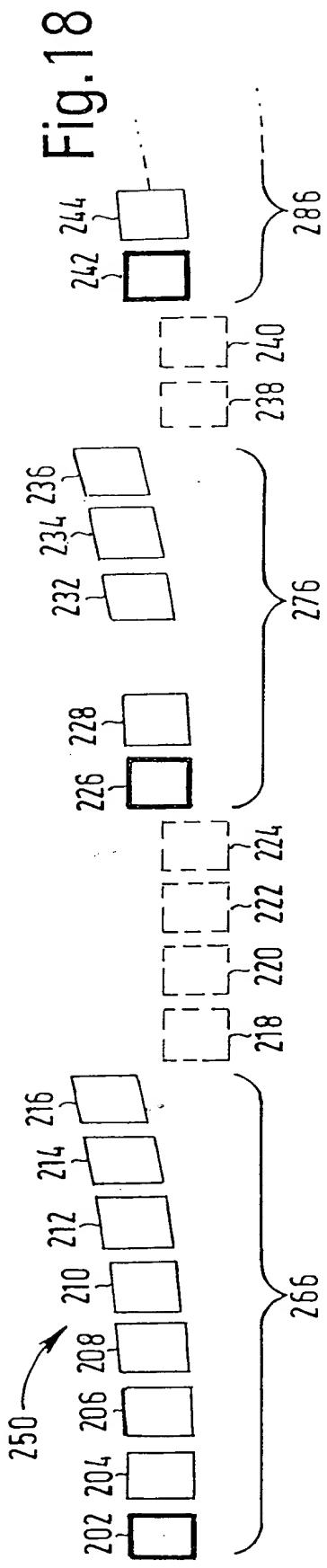
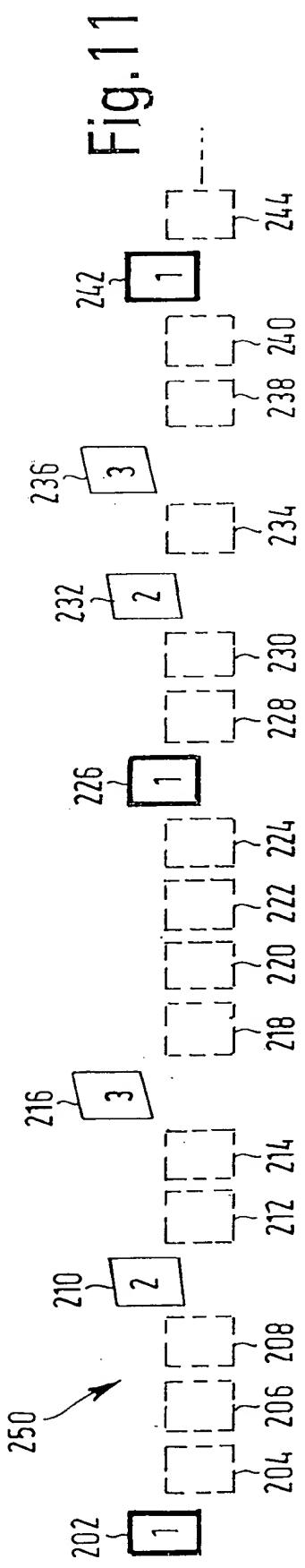


Fig. 10



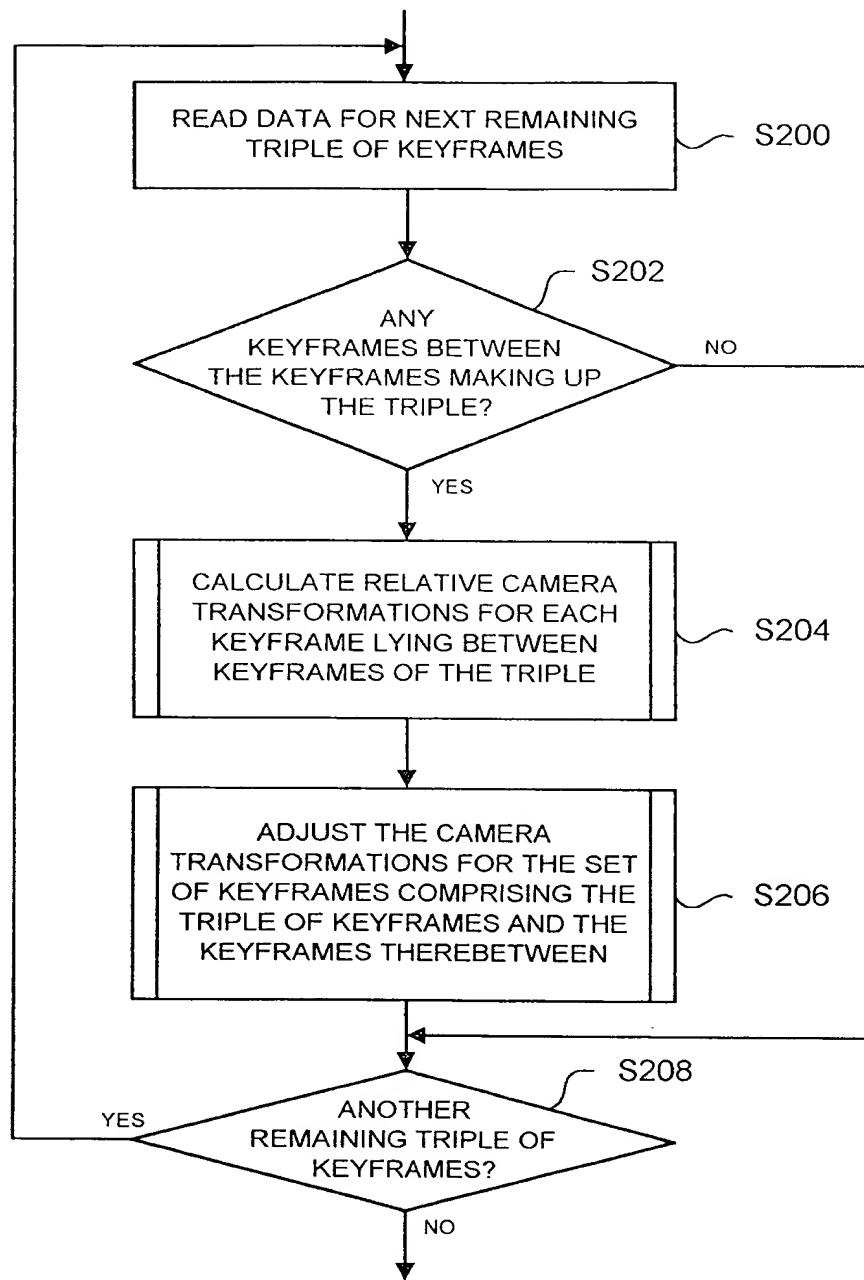


Fig. 12

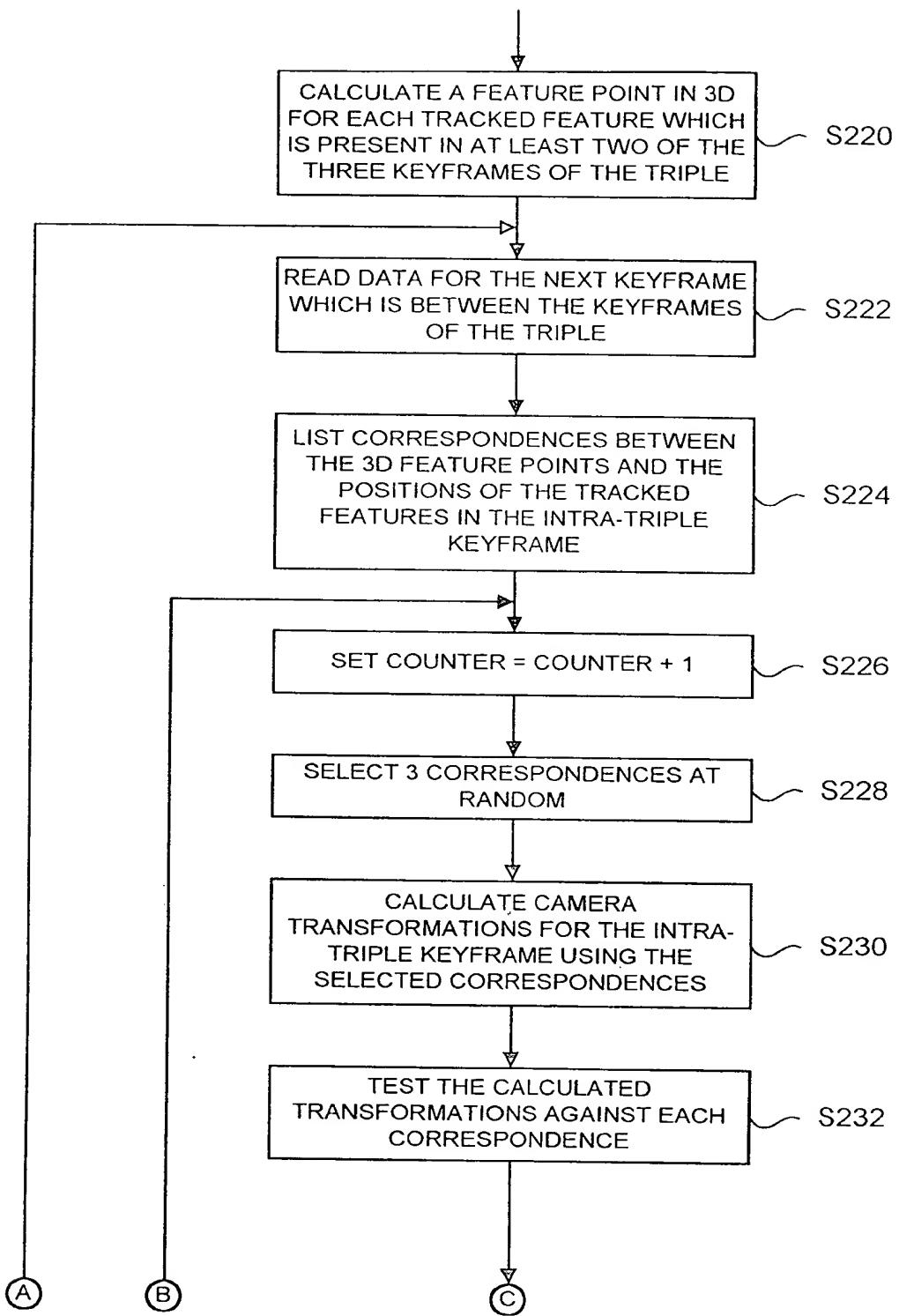
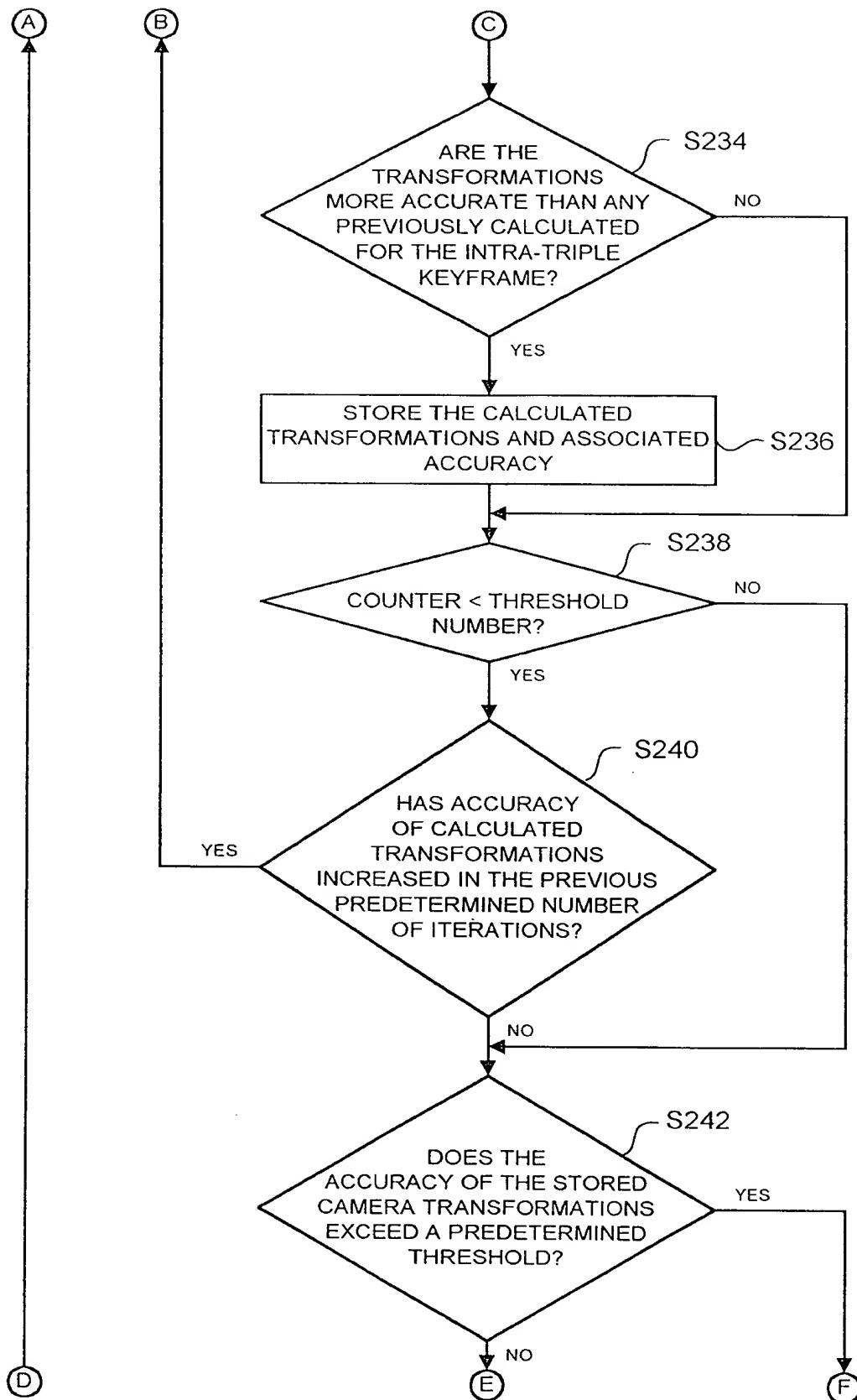


Fig. 13

Fig. 13  
(cont)

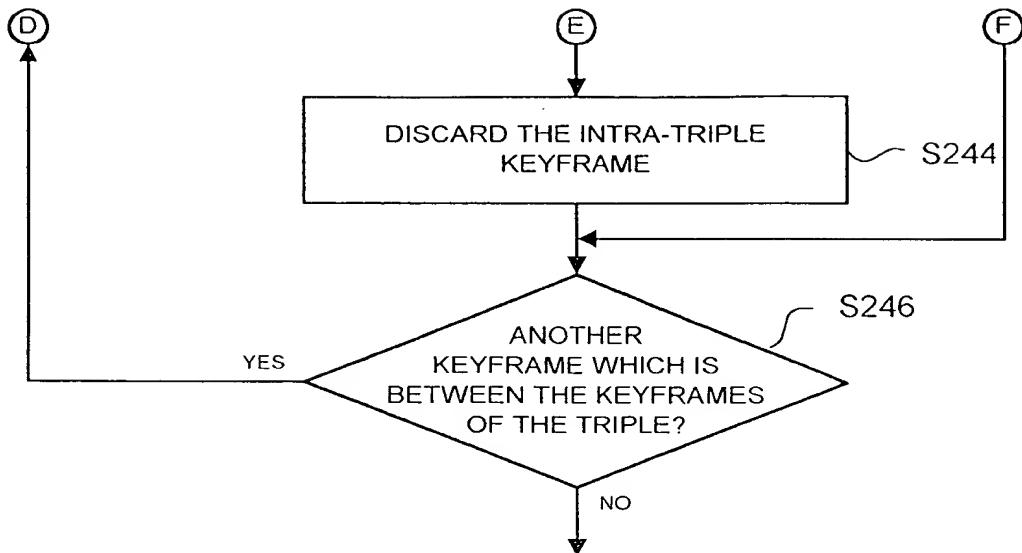


Fig. 13 (cont)

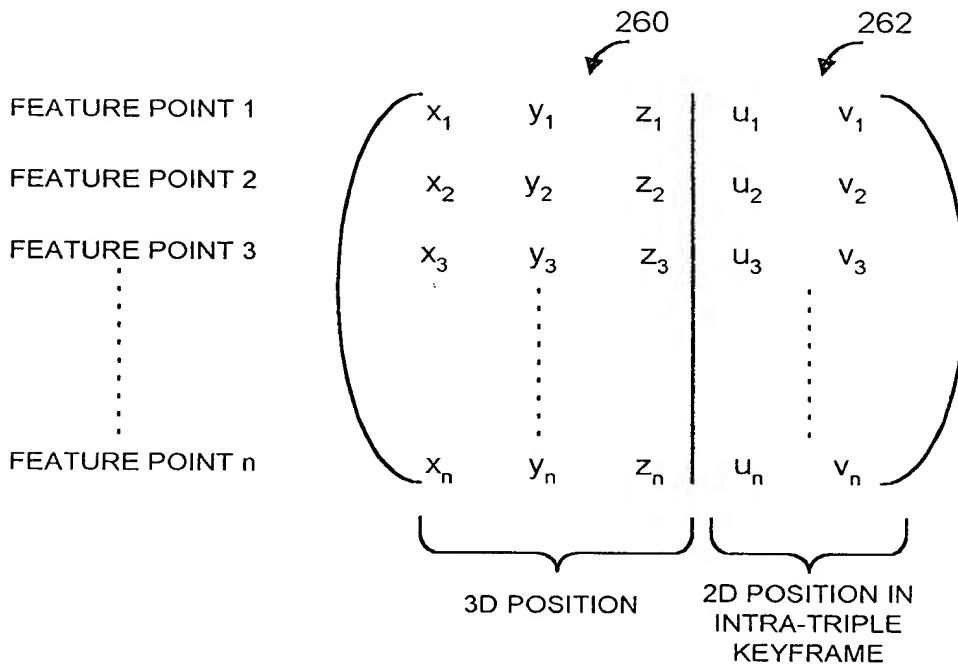
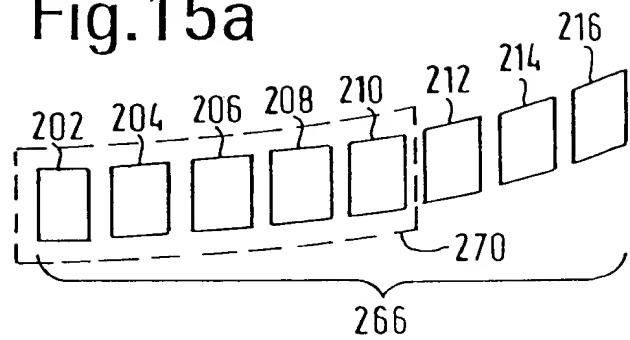
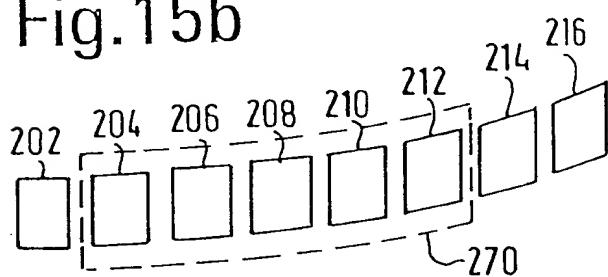
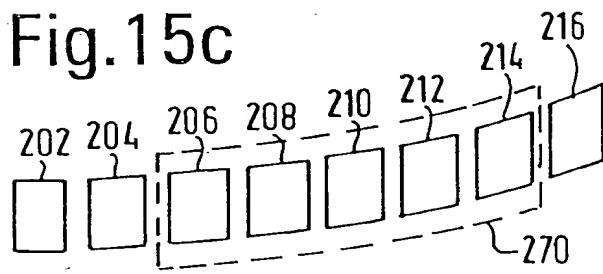
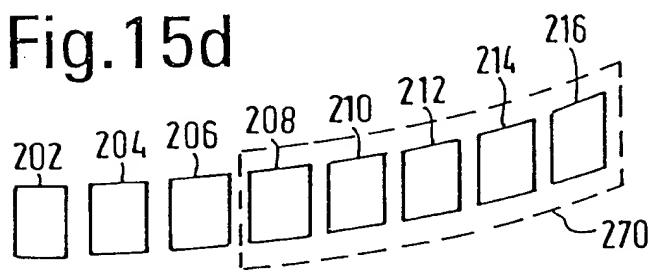


Fig. 14

**Fig.15a****Fig.15b****Fig.15c****Fig.15d**

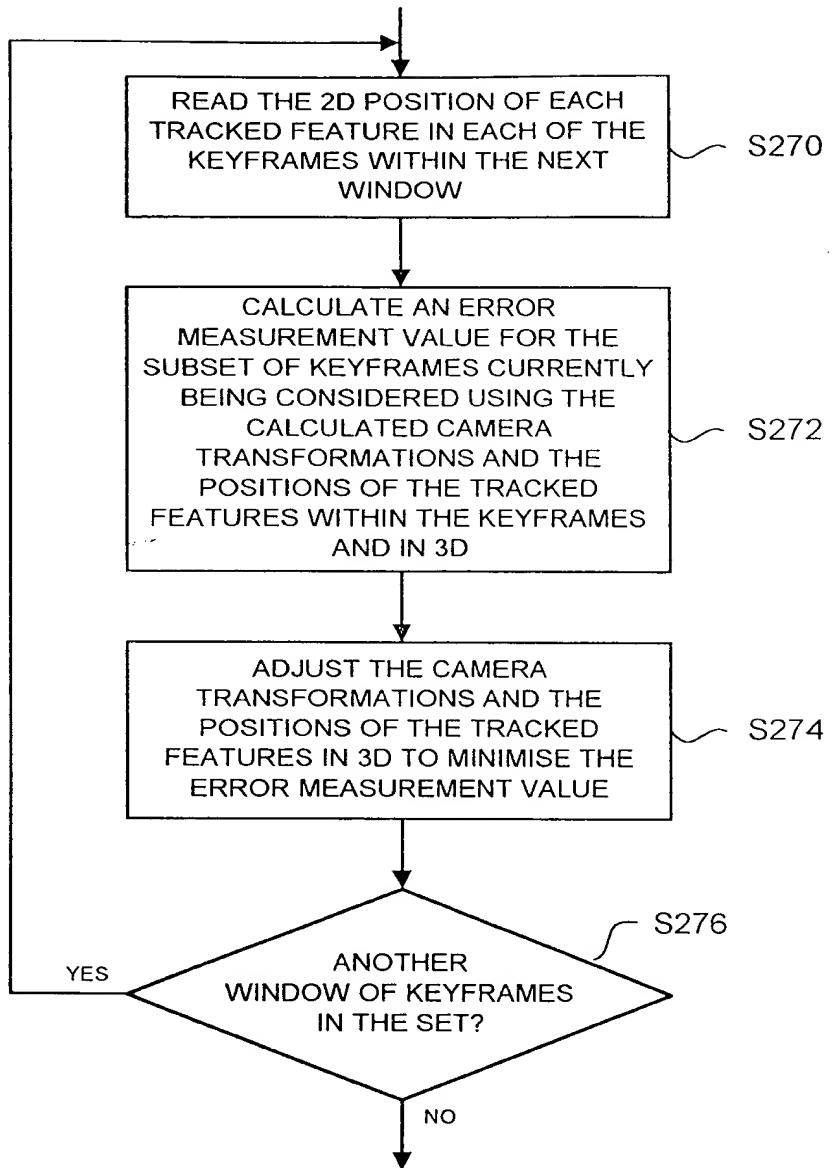
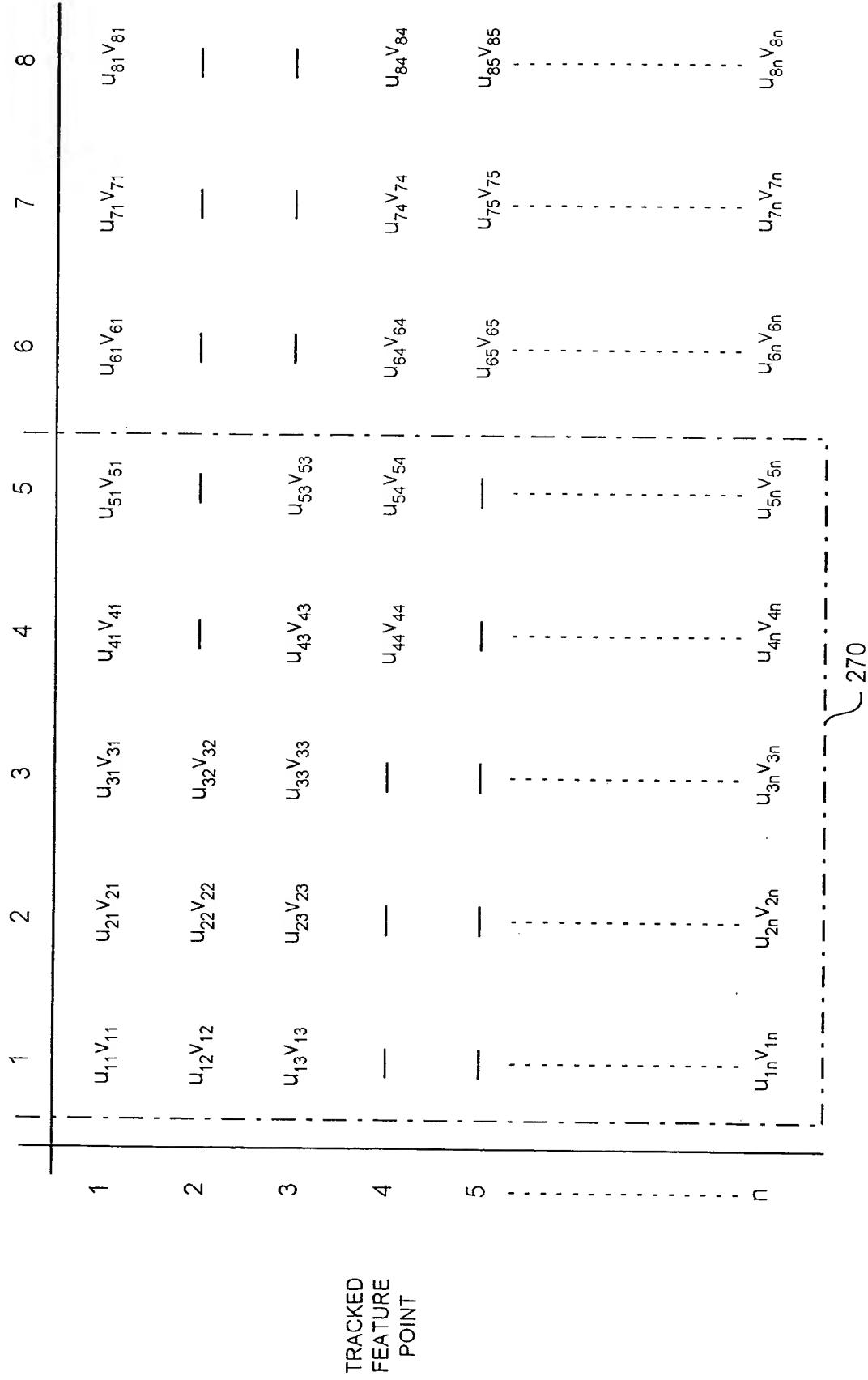


Fig. 16

### KEYFRAME WITHIN SET



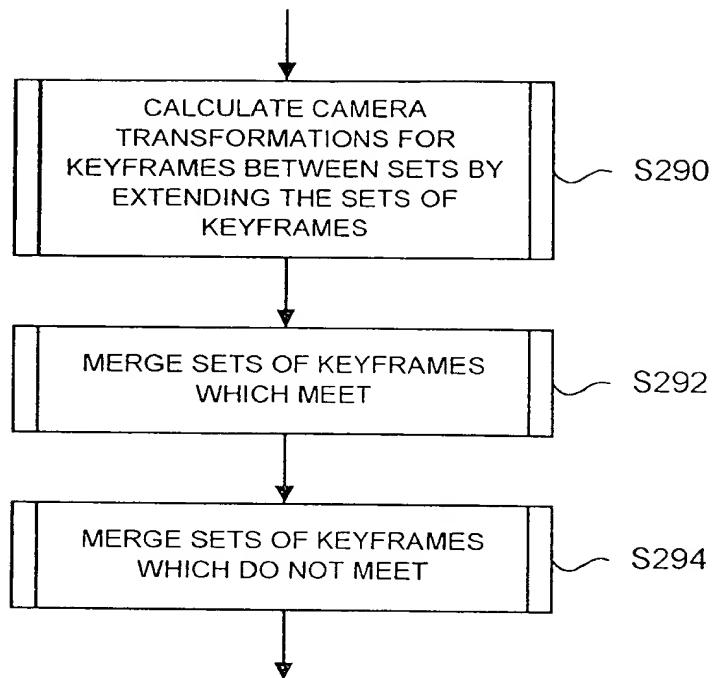


Fig. 19

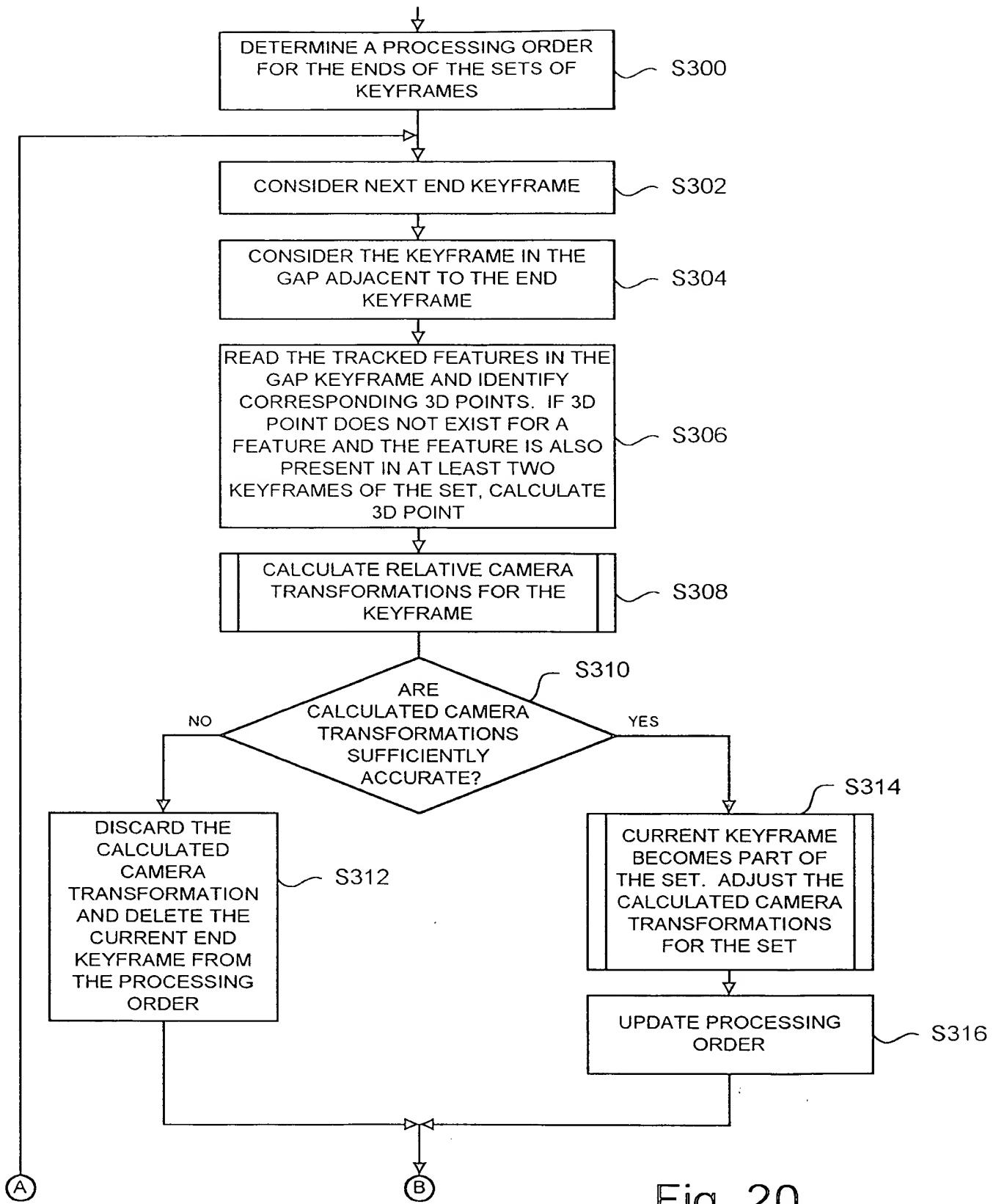


Fig. 20

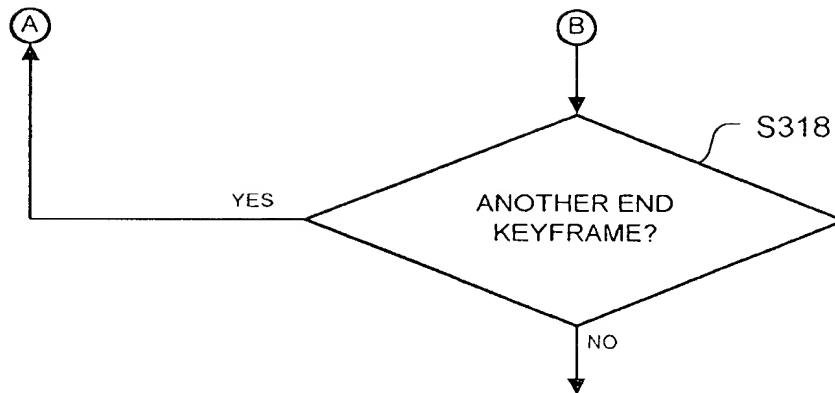


Fig. 20 (cont)

ECE 544: Embedded Systems - Lab 3: Kalman Filter

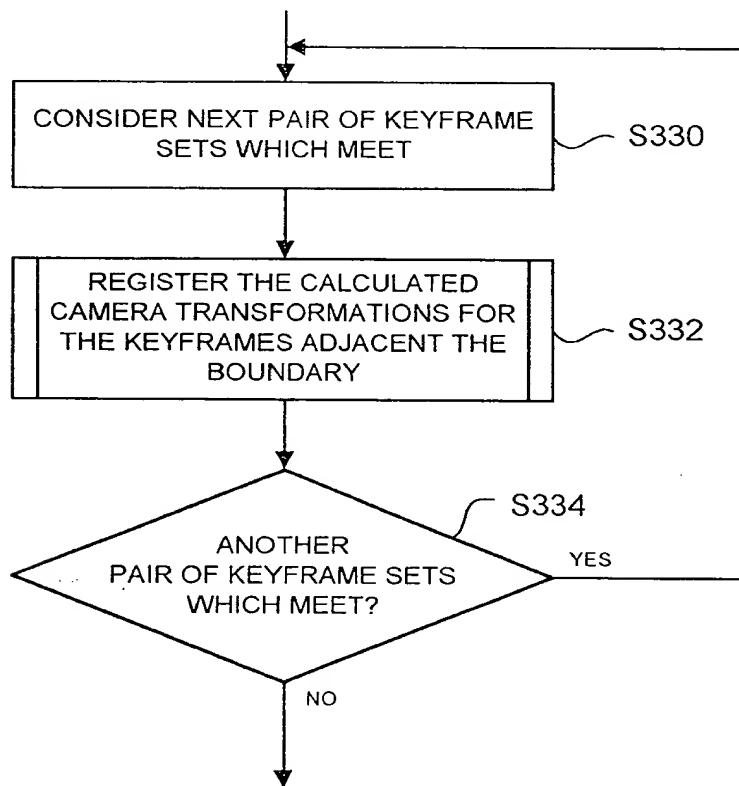


Fig. 22

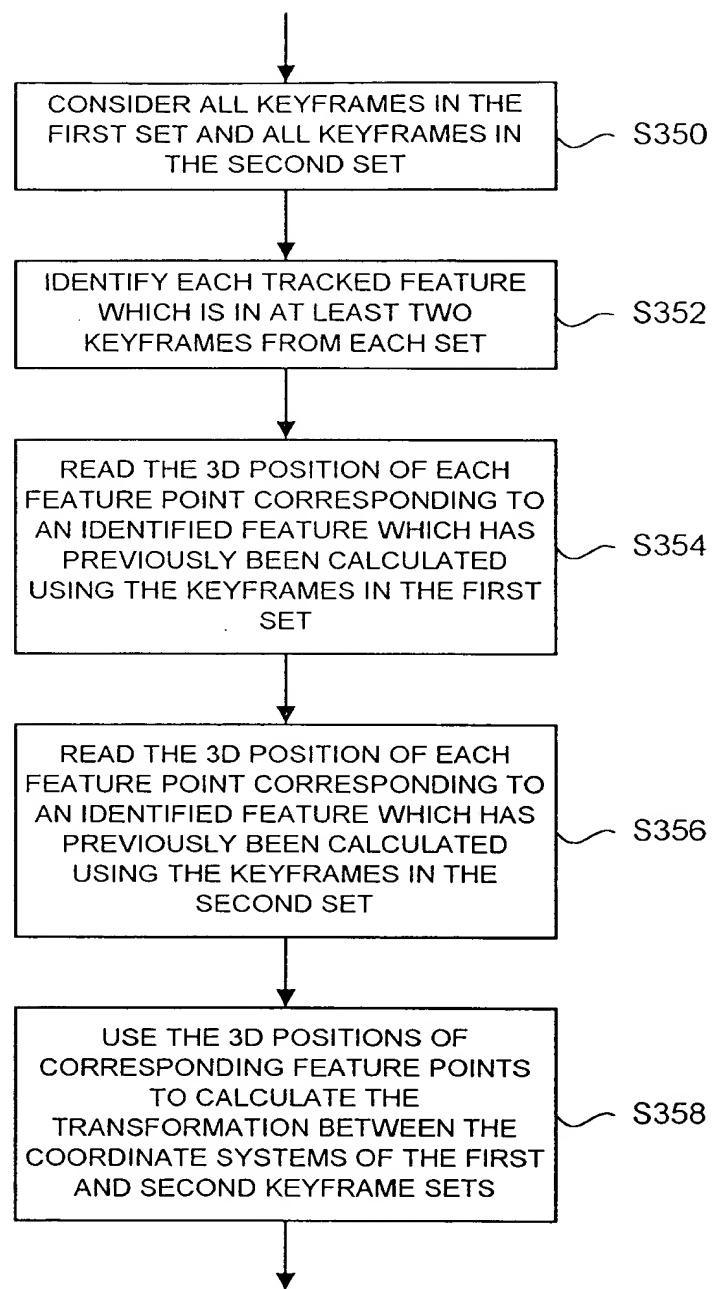
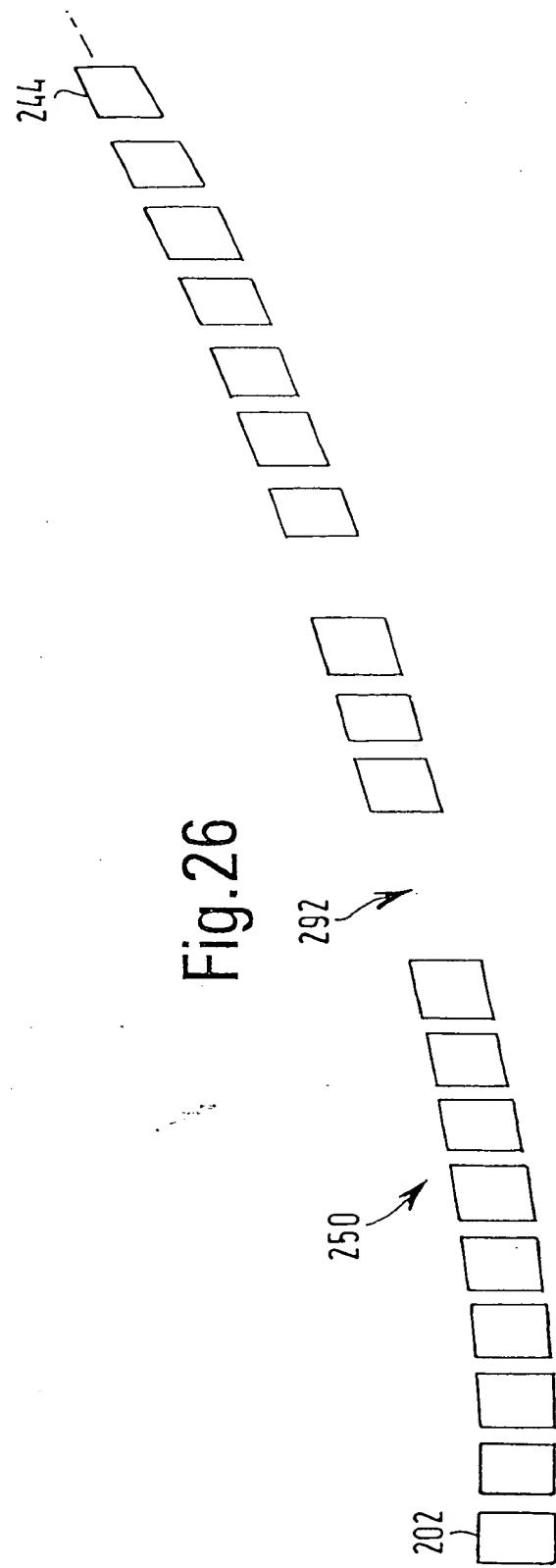
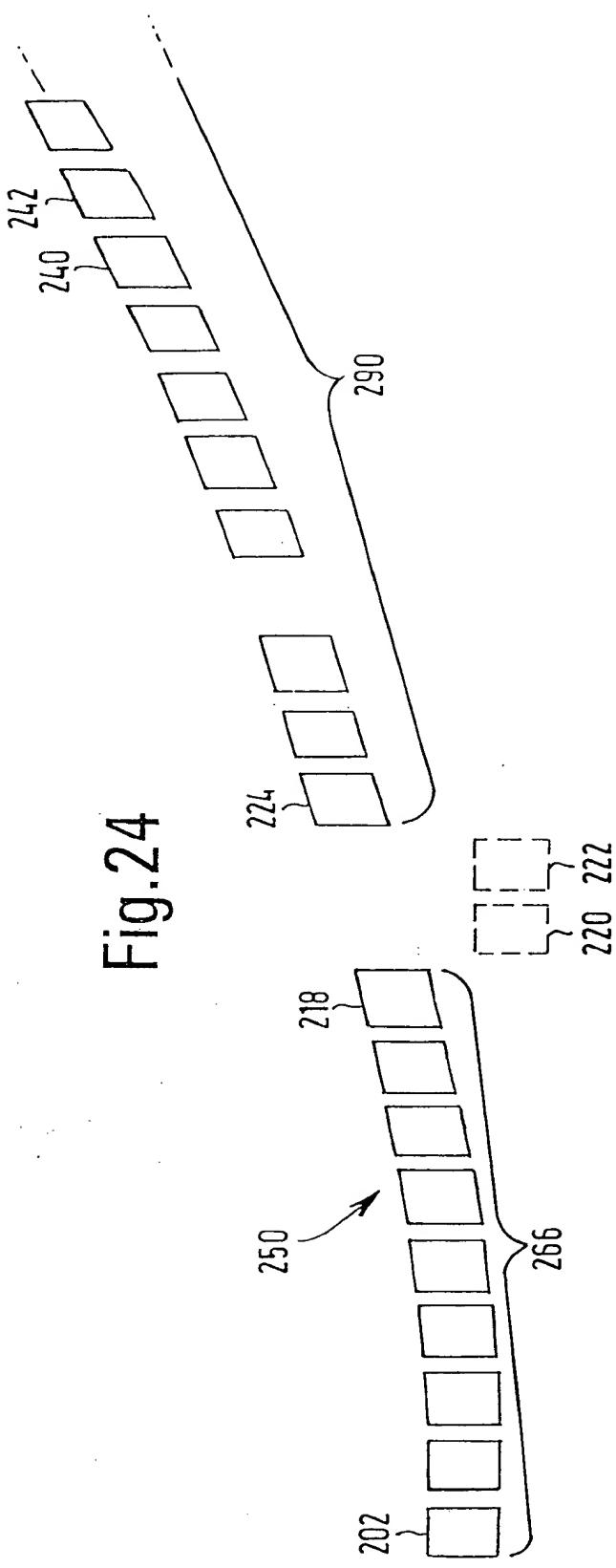


Fig. 23



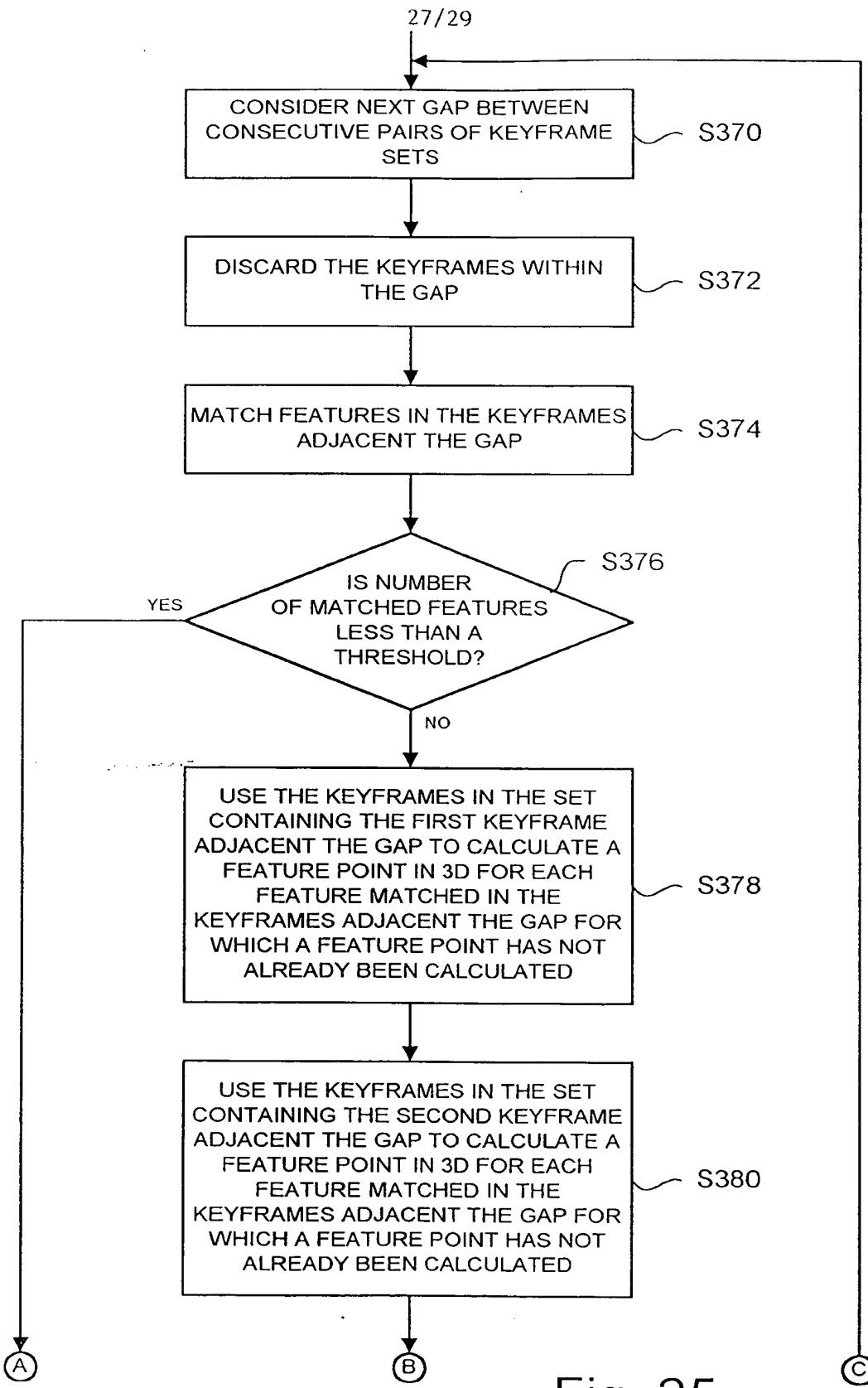


Fig. 25

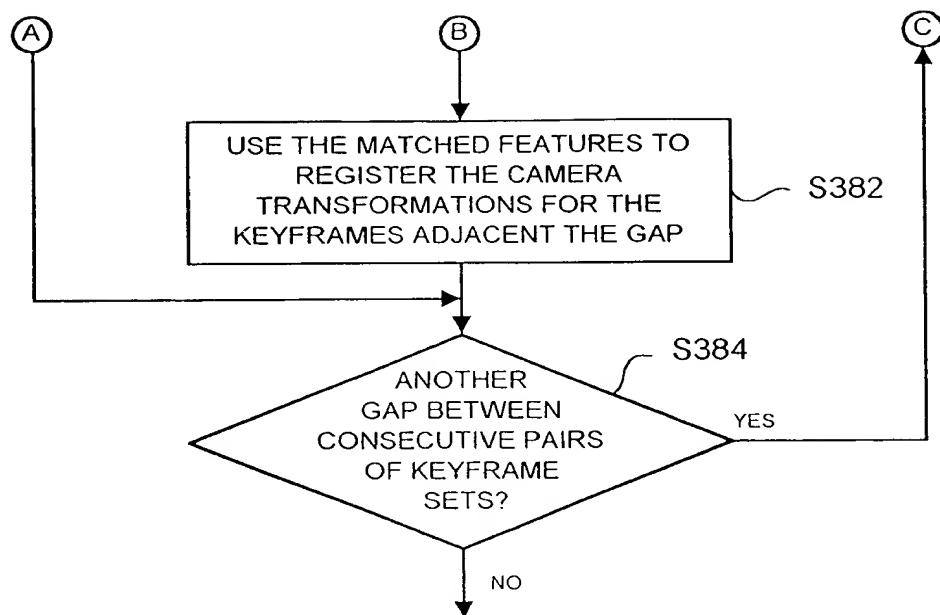


Fig. 25 (cont)

